

**AS1056 - Mathematics  
for Actuarial Science.  
Chapter 11, Tutorial 1.**

Emilio Luis Sáenz Guillén

Faculty of Actuarial Science  
and Insurance,  
Bayes Business School.

12/02/2025



## Refreshing some concepts: Eigenvalues and eigenvectors

Let  $A$  be a linear transformation represented by a matrix. If there is a vector  $\mathbf{v} \in \mathbb{R}^n \neq \mathbf{0}$  such that

$$A\mathbf{v} = \lambda\mathbf{v} \quad (1)$$

for some scalar  $\lambda$ , then  $\lambda$  is called the **eigenvalue** of  $A$  with corresponding **eigenvector**  $\mathbf{v}$ .

From a geometric perspective:

- $A$  can be thought as a linear transformation:  $\mathbf{u} = A\mathbf{v}$ .
- An eigenvector of matrix  $A$  is a non-zero vector that, under the linear transformation applied by  $A$ , is only scaled (or flipped) by a scalar factor,  $\lambda$ .
- The eigenvalue  $\lambda$  tells you how much the eigenvector  $\mathbf{v}$  is stretched or shrunk after the transformation  $A$ . If  $\lambda > 1$ , the vector is stretched; if  $0 < \lambda < 1$ , it is shrunk. If  $\lambda < 0$ , the vector is also *flipped* in direction.

## Exercise 11.13

- (i) Construct a  $2 \times 2$  matrix  $A$  with all its elements non-zero and having eigenvalues 3 and  $-1$ .
- (ii) The *characteristic equation* of the matrix  $A$  is the polynomial satisfied by the eigenvalues, i.e.,

$$\lambda^2 - 2\lambda - 3 = 0.$$

Show that

$$A^2 - 2A - 3I = \mathbf{O},$$

where  $\mathbf{O}$  is a matrix with every element equal to 0.

(This is a special case of the “Cayley-Hamilton Theorem”.)

## Cayley-Hamilton Theorem

Let  $A$  be an  $n \times n$  matrix with characteristic polynomial

$$p(\lambda) = \det(A - \lambda I) = \lambda^n + c_{n-1}\lambda^{n-1} + \cdots + c_1\lambda + c_0.$$

The Cayley-Hamilton theorem asserts that the matrix  $A$  satisfies its own characteristic polynomial, that is,

$$p(A) = A^n + c_{n-1}A^{n-1} + \cdots + c_1A + c_0I = \mathbf{O}$$

where  $\mathbf{O}$  is the  $n \times n$  zero matrix.

## Exercise 11.15

The function  $f(\theta)$ , defined on  $\theta \in [0, \pi]$ , is given by the quadratic form

$$f(\theta) = \begin{pmatrix} \cos(\theta) & \sin(\theta) \end{pmatrix} \underbrace{\begin{pmatrix} 6 & 2 \\ 2 & 2 \end{pmatrix}}_A \begin{pmatrix} \cos(\theta) \\ \sin(\theta) \end{pmatrix}.$$

Theory suggests that the **maximum value** of  $f$  over the given range should be equal to the **larger eigenvalue** of matrix  $A$  and the **minimum value** should be equal to the **smaller eigenvalue**.

- (i) Show that one of the turning points of  $f$  is  $\theta = \frac{\pi}{8}$  and that it is a maximum.

## Exercise 11.15

**Hint.** Recall the following trigonometric identities,

- Pythagorean formula for sines and cosines:

$$\sin^2(\theta) + \cos^2(\theta) = 1$$

- Double angle formulas for sine and cosine:

$$\sin(2\theta) = 2 \sin(\theta) \cos(\theta)$$

$$\cos(2\theta) = \cos^2(\theta) - \sin^2(\theta)$$

## Exercise 11.15

- (ii) Determine the eigenvalues of the matrix

$$\begin{pmatrix} 6 & 2 \\ 2 & 2 \end{pmatrix}$$

and verify that  $f\left(\frac{\pi}{8}\right)$  is equal to the larger of them.

- (iii) There is a second turning point in  $[0, \pi]$ . What is it?

## **Bayes Business School**

106 Bunhill Row

London EC1Y 8TZ

Tel +44 (0)20 7040 8600

[bayes.city.ac.uk](http://bayes.city.ac.uk)