

# Augmented Spline Regression for Advanced Data Analysis: Generalized Additive Models & Functional Gradient Boosting with Geometrically Designed (GeD) Splines

Dimitrina S. Dimitrova<sup>1</sup>, Vladimir K. Kaishev<sup>1</sup> and  
Emilio Sáenz Guillén (presenter)<sup>1</sup>

RSS International Conference 2024

<sup>1</sup> Faculty of Actuarial Science and Insurance, Bayes Business School.

Email: [emilio.saenz-guillen@bayes.city.ac.uk](mailto:emilio.saenz-guillen@bayes.city.ac.uk)

# Geometrically Designed Splines (GeDS)

Free-knot spline regression technique based on a ***residual-driven (locally-adaptive) knot insertion scheme*** that produces a piecewise linear spline fit, over which ***smoother higher order spline fits*** are subsequently built (Kaishev et al., 2016, Dimitrova et al., 2023).

✿ GeD spline methodology is extended further by:

1. **GAM-GeDS**: encompassing **Generalized Additive Models (GAM)**, thereby making GeDS highly multivariate.
2. **FGB-GeDS**: incorporating **Functional Gradient Boosting (FGB)**, improving the construction of the underlying spline regression model.

# Geometrically Designed Splines (GeDS)

Free-knot spline regression technique based on a ***residual-driven (locally-adaptive) knot insertion scheme*** that produces a piecewise linear spline fit, over which ***smoother higher order spline fits*** are subsequently built (Kaishev et al., 2016, Dimitrova et al., 2023).

✳ GeD spline methodology is extended further by:

1. **GAM-GeDS**: encompassing **Generalized Additive Models (GAM)**, thereby making GeDS highly multivariate.
2. **FGB-GeDS**: incorporating **Functional Gradient Boosting (FGB)**, improving the construction of the underlying spline regression model.



- Applications in highly multivariate contexts: AI (e.g., image recognition/processing); robotics (e.g. motion planning for humanoid robots).
- Implemented in the R package **GeDS**, available from CRAN: <https://cran.r-project.org/package=GeDS>

## 4. Functional Gradient Boosting with GeDS (FGB-GeDS)

- Functional Gradient Boosting (Friedman, 2001).

\* FGB-GeDS deals with major limitations of mainstream boosting algorithms:

- "Prone to overfitting"
  - ➡ Optimal number of boosting iterations determined by a **stopping rule** based on a ratio of consecutive deviances.
- "Large number of parameters and unstable performance"
  - ➡ Strength of the base learners is **automatically regulated by the GeDS** technique itself, and flexibly controlled through the GeDS parameters.
- "Black-box models"
  - ➡ Final FGB-GeDS boosted model expressed as a **single spline model**, which simplifies its evaluation and enhances interpretability.

## Task: Fourier Transform Computation of Materials Science Data

Given a sample,  $\mathcal{L} = \{F(Q_i), Q_i\}_{i=1}^N$ ,  $0 < Q_1 < \dots < Q_N < \tilde{Q}_{\max}$ , we are interested in estimating the **Fourier transform** (imaginary part):

$$G(r) = \frac{2}{\pi} \int_0^{Q_{\max}} F(Q) \sin(Qr) dQ.$$

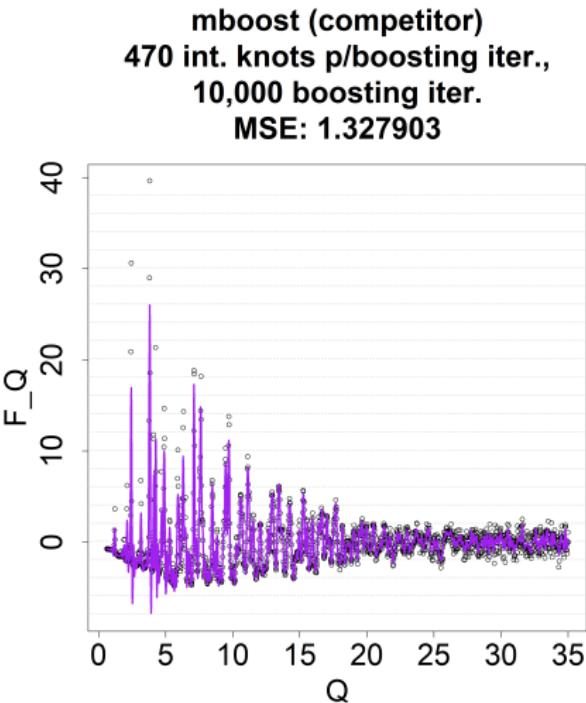
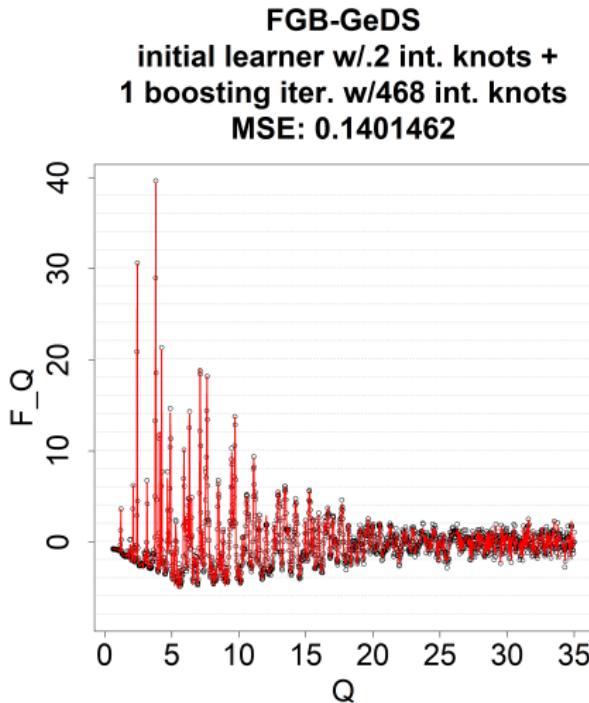
**Assuming  $Q_{\max}$  is known, this involves two steps:**

- Step 1.** Estimate  $F(Q)$  through a GeDS fit  $\equiv S(Q)$  to the sample  $\mathcal{L}$ .
- Step 2.** Compute  $G(r)$  using the fitted GeDS model,  $S(Q)$ .

For the time being, let us assume  $Q_{\max} \equiv \tilde{Q}_{\max}$ , though in general  $Q_{\max} < \tilde{Q}_{\max}$ :

- ➡ Signal in the data prevails up to a certain point; beyond this, only noise remains.
- ➡ Sequential (and costly) data collection: cut off at the appropriate  $Q_{\max}$  for an optimal experimental design.

## Step 1. Fit $F(Q)$ , e.g, with an FGB-GeDS model



## Step 2. Compute the Fourier transform of gold

### Proposition

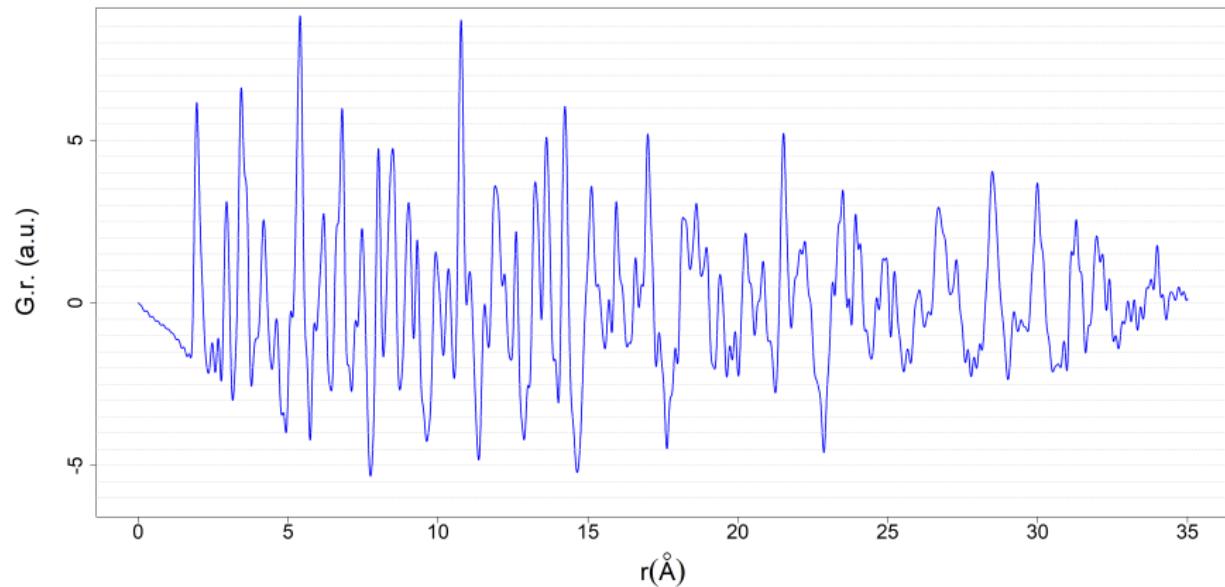
For the  $\sin()$  transform,

$$G(r) = \frac{2}{\pi} \int_0^{Q_{\max}} F(Q) \sin(Qr) dQ$$

of the function  $F(Q)$ , approximated by  $S(Q)$  of order  $n = 2s$ ,  $s = 1, 2, 3, \dots$  we have

$$G(r) \approx \frac{(-1)^s 2(n-1)!}{\pi r^n} \sum_{i=1}^p \hat{\theta}_i (t_{i+n} - t_i) \sum_{j=i}^{i+n} \frac{\sin(t_j r)}{\prod_{\substack{l=i \\ l \neq j}}^{i+n} (t_j - t_l)},$$

where  $r \in \mathbb{R}^+$ ,  $p = k + n$ ;  $\hat{\theta}_i$ ,  $i = 1, \dots, p$  are the GeDS regression coefficients.

Step size of  $r$  is 0.01

 Dimitrova, D. S., Kaishev, V. K., Lattuada, A., & Verrall, R. J. (2023). Geometrically designed variable knot splines in generalized (non-)linear models. *Applied Mathematics and Computation*, 436, 127493.

<https://doi.org/https://doi.org/10.1016/j.amc.2022.127493>

 Friedman, J. H. (2001). Greedy function approximation: A gradient boosting machine.. *The Annals of Statistics*, 29(5), 1189–1232.

<https://doi.org/10.1214/aos/1013203451>

 Kaishev, V. K., Dimitrova, D. S., Haberman, S., & Verrall, R. J. (2016). Geometrically designed, variable knot regression splines. *Computational Statistics*, 31(3), 1079–1105. <https://doi.org/10.1007/s00180-015-0621-7>