

Enhancing Geometrically Designed Spline (GeDS) Regression through Generalized Additive Models and Functional Gradient Boosting

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2. GeDS estimation method

3. Generalized Additive Models with GeDS

4. Functional Gradient Boosting with GeDS

4.1 Simulated data

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5. Insurance data

1. Motivation

- ✱ **Geometrically Designed Splines (GeDS)** (Kaishev et al., [2016](#), Dimitrova et al., [2023](#)), — accurate and efficient tool for regression problems involving one or two covariates.

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- ✱ GeD spline methodology is extended further by:
 1. **GAM-GeDS**: encompassing **Generalized Additive Models (GAM)**, thereby making GeDS highly multivariate.
 2. **FGB-GeDS**: incorporating **Functional Gradient Boosting (FGB)**, improving the construction of the underlying spline regression model.

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- Applications in highly multivariate contexts: AI (e.g., image recognition/processing); robotics (e.g. motion planning for humanoid robots).
 - Implemented in the R package **GeDS**, available from CRAN:
<https://cran.r-project.org/package=GeDS>

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GeDS method unfolds into two phases:

- **STAGE A** constructs a least squares linear spline fit to the data.
 - ▶ Starting with a straight-line, LS fit, which is then sequentially “broken” by iteratively introducing knots at those points ‘where the fit deviates most from the underlying functional shape determined by the data’, based on a measure defined by residuals.

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- **STAGE B**
 - ▶ Builds smoother higher order spline fits using Schoenberg’s variation diminishing spline (VDS) approximation, based on the linear fit from Stage A.
 - ▶ For each higher spline order (quadratic, cubic...), compute the *averaging knot location* and re-estimate the spline coefficients by LS.

Properties of GeDS estimated knots and regression coefficients:

- ✱ *Schoenberg variation diminishing optimality* of the estimated knots (Kaishev et al., 2006b).
- ✱ *Asymptotic normality* of estimators in the case of normal noise, which allows for the construction of pointwise asymptotic confidence intervals that effectively converge (Kaishev et al., 2006a).
- ✱ Asymptotic conditions on the rate of growth of the knots for *negligible bias/variance ratio* (Kaishev et al., 2006a).

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3. Generalized Additive Models with GeDS

The **Generalized Additive Model (GAM)** assumes the response variable, $Y \sim E.F.$, and relates its conditional expectation, $\mu = \mathbb{E}[Y|X]$, to the predictor variables, X_1, \dots, X_P , via a link function $g(\cdot)$:

$$g(\mu) = \alpha + \sum_{j=1}^P f_j(X_j), \text{ with } \mathbb{E}[f_j(X_j)] = 0, \quad j = 1, \dots, P \quad (1)$$

Hastie and Tibshirani, 1990 — *local-scoring* and *backfitting* algorithms in conjunction with scatterplot smoothers, to fit GAMs.

GAM with GeD Splines: Local-scoring algorithm using GeD splines as the function smoothers, f_j , within the backfitting algorithm.

3.1. Simulated data application

Consider the function (Gu and Wahba, 1991):

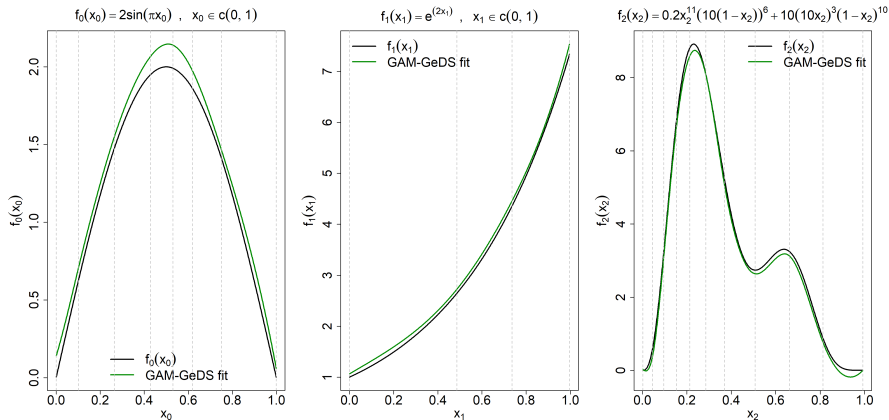
$$f(\mathbf{x}) = \underbrace{2 \times \sin(\pi \times x_0)}_{f_0(x_0)} + \underbrace{\exp(2x_1)}_{f_1(x_1)} + \underbrace{0.2x_2^{11}(10(1-x_2))^6 + 10(10x_2)^3(1-x_2)^{10}}_{f_2(x_2)}$$

- **Example 1:** Fit $y = f(\mathbf{x}) + \epsilon$, $\epsilon \sim \mathcal{N}(0, \sigma_\epsilon^2)$, and also include a noise predictor x_3 .
- **Example 2:** replace $f_0(x_0)$ by a factor variable x_0 with 4 levels.

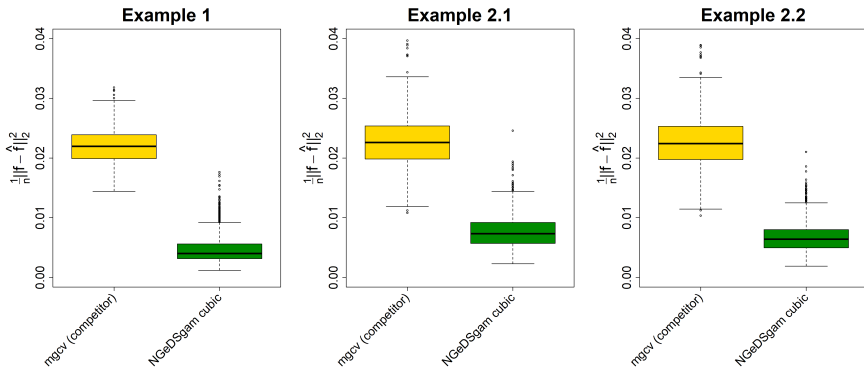
- ▶ **2.1:** Include the noise predictor x_3 .
- ▶ **2.2:** Delete the noise predictor x_3 .

➡ Generate 1,000 random samples, $\{X_i, Y_i\}_{i=1}^N$, with $N = 400$ for example 1 and $N = 200$ for example 2; $x_0, x_1, x_2, x_3 \sim \text{Uniform}(0, 1)$.

Example 1: GAM-GeDS (partial) fits



Example 1, 2.1 & 2.2: MSE boxplots



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4. Functional Gradient Boosting with GeDS

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- **“Large number of parameters and unstable performance”**
 - ➡ Strength of the base learners is **automatically regulated by the GeDS** methodology and flexibly controlled through the GeDS parameters.

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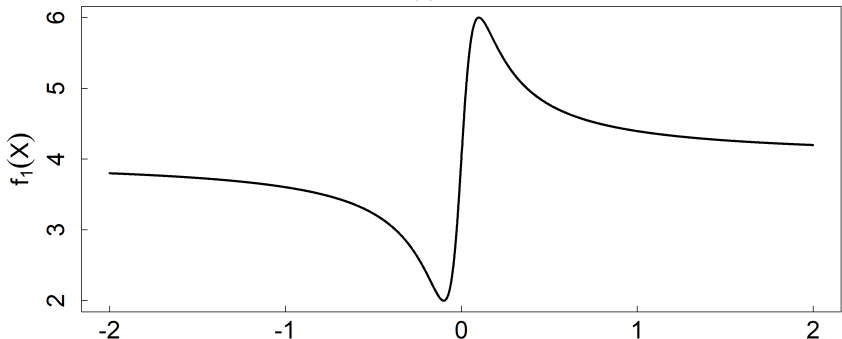
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- **“Large number of parameters and unstable performance”**
 - ➡ Strength of the base learners is **automatically regulated by the GeDS** methodology and flexibly controlled through the GeDS parameters.
- **“Black-box models”**
 - ➡ Final FGB-GeDS boosted model expressed as a **single spline model**, which simplifies its evaluation and enhances interpretability.

4.1. Simulated data application

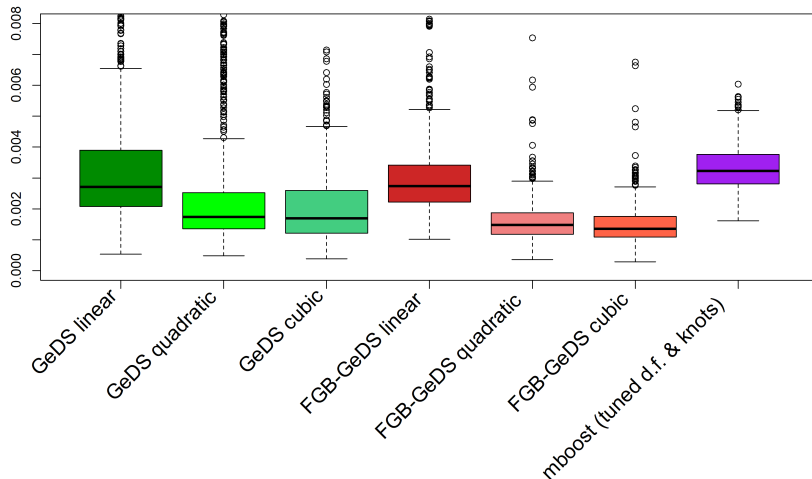
Consider the following function:

$$f_1(x) = 40 \frac{x}{1 + 100x^2} + 4, \quad x \in (-2, 2)$$

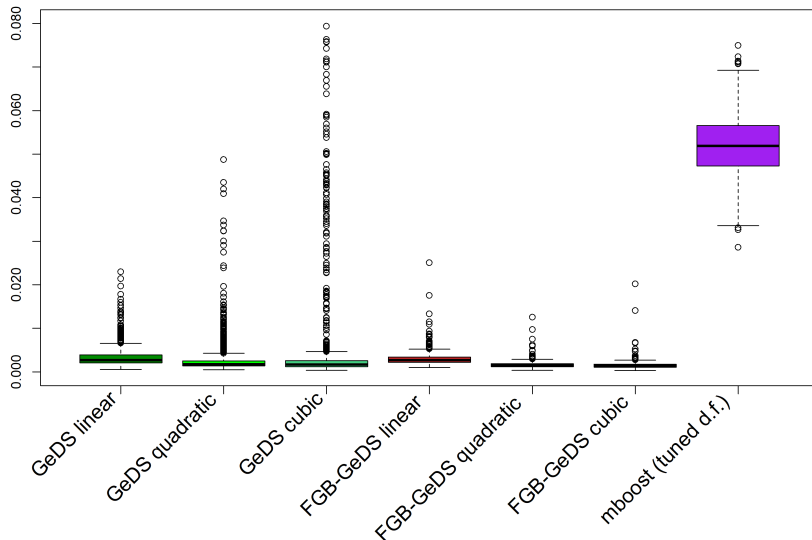


➔ For each, generate 1,000 random samples, $\{X_i, Y_i\}_{i=1}^N$ with $Y_i \sim \mathcal{N}(\mu_i, \sigma)$, $\sigma = 0.2$, $\mu_i = \eta_i = f_1(X_i)$.

GeDS	10 int. knots
FGB-GeDS	Init. learner with 2 int. knots + 1 boosting iter. with 8 int. knots
mboost (competitor)	10,000 boosting iter. with 36 int. knots per iter.



➡ And setting **mboost** to have 10 int. knots p/boosting iter. (i.e., \simeq **FGB-GeDS**):



4.2 Task: Fourier Transform Computation of Materials Science Data

Given a sample, $\mathcal{L} = \{F(Q_i), Q_i\}_{i=1}^N$, $0 < Q_1 < \dots < Q_N < \tilde{Q}_{\max}$, we are interested in estimating the **Fourier transform** (imaginary part):

$$G(r) = \frac{2}{\pi} \int_0^{Q_{\max}} F(Q) \sin(Qr) dQ.$$

Assuming Q_{\max} is known, this involves two steps:

Step 1. Estimate $F(Q)$ through a GeDS fit $\equiv S(Q)$ to the sample \mathcal{L} .

Step 2. Compute $G(r)$ using the fitted GeDS model, $S(Q)$.

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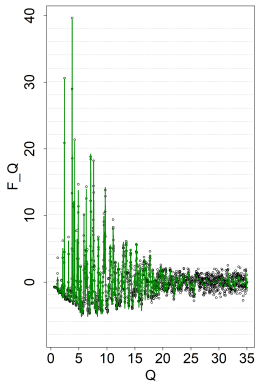
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For the time being, let us assume $Q_{\max} \equiv \tilde{Q}_{\max}$, though in general $Q_{\max} < \tilde{Q}_{\max}$:

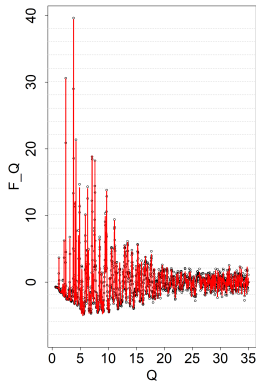
- ➡ Signal in the data prevails up to a certain point; beyond this, only noise remains.
- ➡ Sequential (and costly) data collection: cut off at the appropriate Q_{\max} for an optimal experimental design.

Step 1. Fit $F(Q)$, e.g, with a GeDS model

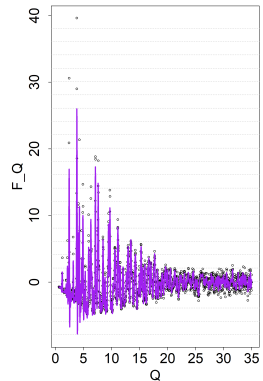
NGeDS
231 knots
MSE: 0.4137057

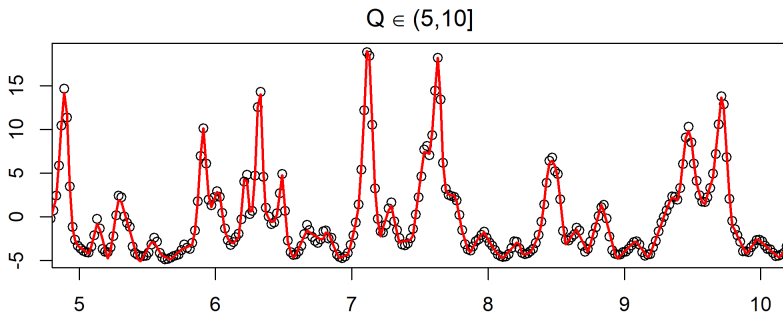
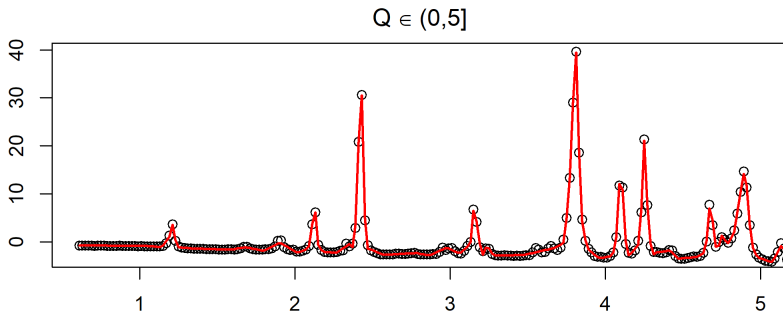


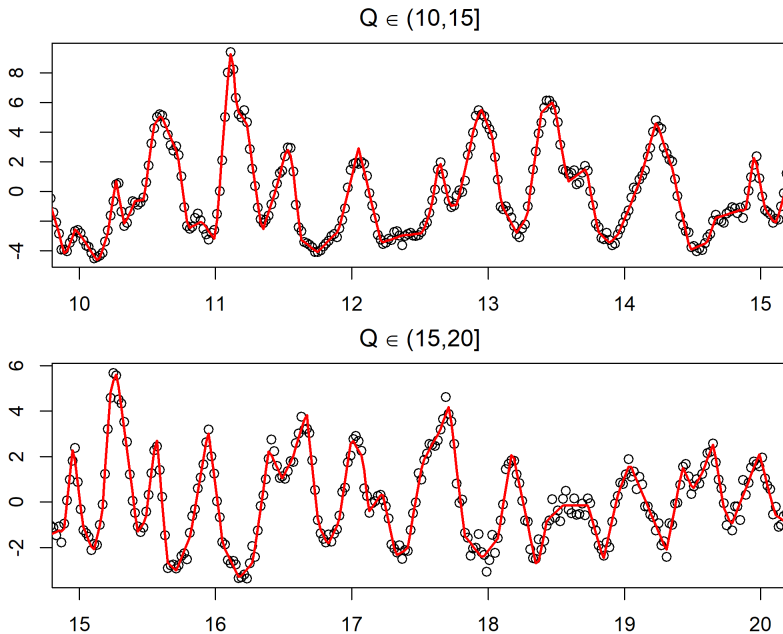
NGeDSboost
initial learner w/.2 int. knots +
1 boosting iter. w/468 int. knots
MSE: 0.1401462

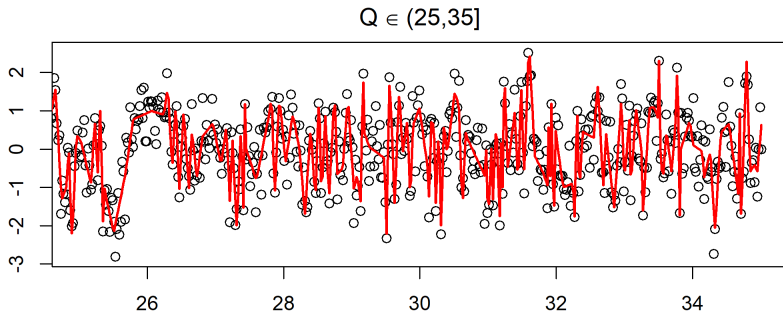
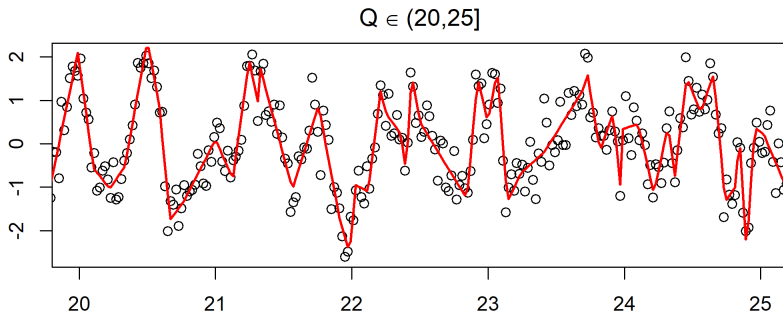


mboost
470 int. knots p/boosting iter.,
10,000 boosting iter.
MSE: 1.327903









Step 2. Compute the Fourier transform

Proposition

For the $\sin(\cdot)$ transform,

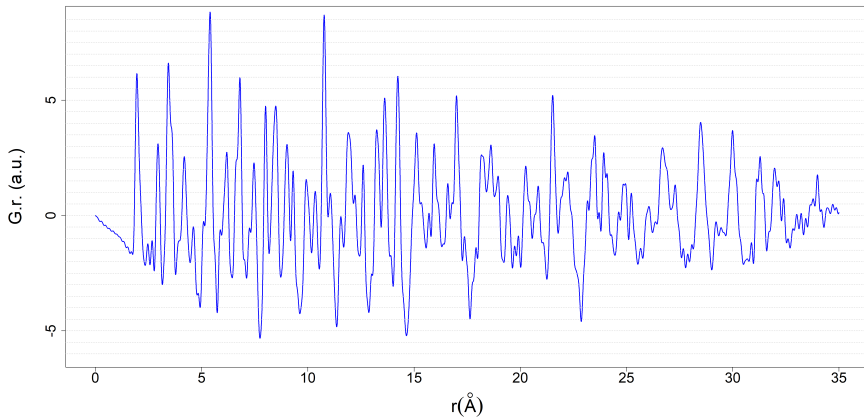
$$G(r) = \frac{2}{\pi} \int_0^{Q_{\max}} F(Q) \sin(Qr) dQ$$

of the function $F(Q)$, approximated by $S(Q)$ of order $n = 2s$, $s = 1, 2, 3, \dots$ we have

$$G(r) \approx \frac{(-1)^s 2(n-1)!}{\pi r^n} \sum_{i=1}^p \hat{\theta}_i (t_{i+n} - t_i) \sum_{j=i}^{i+n} \frac{\sin(t_j r)}{\prod_{\substack{l=i \\ l \neq j}}^{i+n} (t_j - t_l)},$$

where $r \in \mathbb{R}^+$, $p = k + n$; $\hat{\theta}_i$, $i = 1, \dots, p$ are the GeDS regression coefficients.

Step size of r is 0.01



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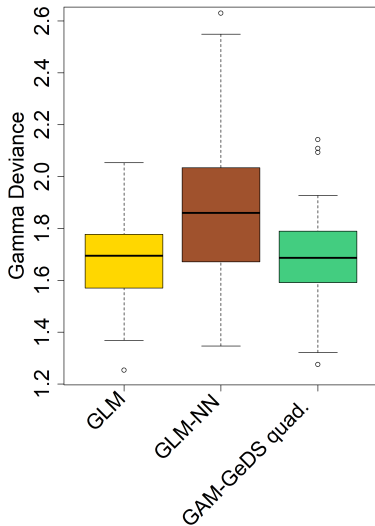
5. Insurance data application

Motorcycle insurance data `swmotorcycle` available through the R package `CASdatasets` (Dutang and Charpentier, 2020).

—→ We follow Delong et al., 2021 and model **gamma claim sizes**:

- ① Gamma GLM regression + Gamma Neural Network regression.
 - ② `mboost`: FGB with P-splines.
 - ③ GAM-GeDS.
 - ④ FGB-GeDS.
- *Response*: `ClaimAmount/ClaimNb`, i.e., the average claim size.
 - *Covariates*: `OwnerAge`; `Gender`; `Area`, `RiskClass`; `VehAge`.
 - *Train/Test split*: **80%/20%**.
 - ▶ Simulate 100 different splits of data.

GLM/GAM Models



Boosting Models

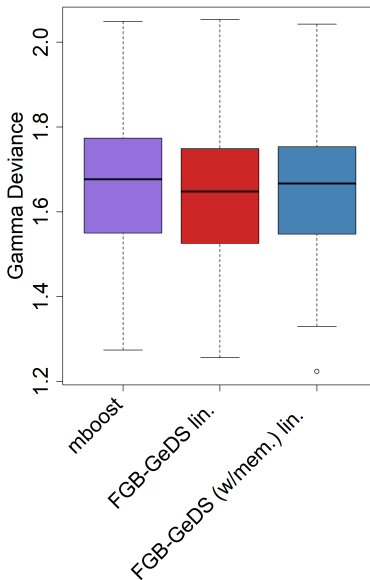


Table 1: GLM/GAM Models









	Gamma Deviance		Time (sec.)	Internal knots (OwnerAge+VehAge)
	Train Data	Test Data		
GLM	1.585727	1.694797	0.008708	-
GLM NN	1.719903	1.859394	167.224576	-
GAM-GeDS quadratic	1.557612	1.686492	0.671260	5

Table 2: Boosting Models

	Gamma Deviance		Time (sec.)	Internal knots p/boosting iter. (OwnerAge+VehAge)	Boosting iterations
	Train Data	Test Data			
mboost	1.610290	1.676810	0.156095	4	100
FGB-GeDS linear (2 starting knots)	1.575972	1.648345	0.130963	2	1
FGB-GeDS w/mem. linear (1 starting knot)	1.575536	1.667158	0.129040	1	3

Concluding remarks

- ✱ GeDS is able to perform well both with more intricate, wiggly data, as well as with more disperse data.
- ✱ Broad scope of applications (insurance data, materials science data)
Further extensions:
 - ▶ Quantile regression (Hendricks and Koenker, [1992](#)).
 - ▶ Varying coefficients regression (Hastie and Tibshirani, [1993](#)).
 - ▶ Density estimation.

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